



STOP

Seguranças robóticas coOperativas

The general goal of the STOP project is to contribute to the acceptance of mobile robotics technologies in the service area, via the installation of mobile robot teams in large indoor areas populated by people (e.g., large stores, shopping centers, offices, museums, etc.) to carry out independent patrolling and surveillance missions.

CLOUD ROBOTICS

Supervision & Monitoring
Teleoperation & Control
Management & Maintenance

COOPERATIVE ROBOTIC GUARDS

Planning & Navigation
Multi-robot patrolling
Detection of abnormal situations